

Smart and Autonomous Systems (S&AS) NSF 16-608

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The S&AS Team

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Welcome

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Outline

- Overview of S&AS Program
- FY 2017 Solicitation
- Program Scope
- Submitting Proposals
- Questions



Autonomy: Definitions

- Independence in one's thoughts or actions, especially moral independence
- Autonomous systems can make choices free of outside influence
- Autonomy refers to the ability of a system to operate and adapt to changing circumstances with reduced or without human control
 - From: "Preparing for the Future of Artificial Intelligence"



Need

- Increasing interest and need for autonomous systems
 - Robots, vehicles, sensor networks, smart infrastructure, ...
 - Manufacturing, health-care, service, exploration, monitoring, sustainability,...
- Need to minimize human intervention
 - Systems should self-monitor and report problems
 - Note: intervention distinguished from interaction
- Need for adaptation
 - Deal with new problems and opportunities
 - Deal with changes to system hardware and environment, over time
- Need to consider and maintain social good
 - Ethical behavior in the face of conflicting mission and societal goals



Need

- Recent reports highlight the need for autonomy and ethical behavior in intelligent systems
 - NSF Workshop on Future Directions in Cyber-Physical Systems, Robotics, and Autonomy
 - http://dl.acm.org/citation.cfm?id=2904482
 - OSTP reports: "Preparing for the Future of Artificial Intelligence" and "National AI R&D Strategic Plan"
 - https://www.whitehouse.gov/blog/2016/10/12/ administrations-report-future-artificial-intelligence
 - One Hundred Year Study on Artificial Intelligence
 - https://ai100.stanford.edu/



Goal

- Promote fundamental research into Intelligent Physical Systems (IPS)
 - Focus on autonomy
- IPS: Integrated hardware and software systems that interact with physical environments and exhibit five identifying characteristics
 - Cognizant
 - Taskable
 - Reflective
 - Ethical
 - Knowledge-Rich

These characteristics are the **research themes** of S&AS



Cognizant

- IPS that are aware of their capabilities and limitations
 - Capable of operating autonomously over extended periods of time, with minimal or no human supervision
 - Acting in a manner that is understandable by human collaborators
 - Includes explaining themselves and asking for help, when needed
- Example:
 - A fully autonomous vehicle that knows when the conditions of the environment, or the vehicle itself, are incompatible with self-driving

Taskable

- IPS that handle high-level, often vague, instructions
 - Translate directives into suitable plans for sensing, reasoning, communicating, and acting
 - Accept instructions through various modalities
 - Includes natural language dialog, gesture, sketches, multimodal, ...
 - Take initiative to achieve necessary or important tasks
 - Capable of performing multiple tasks concurrently
- Example:
 - An underwater glider is tasked with mapping the routes of fish, surfacing every few days



Reflective

- IPS that learn from experience to improve performance
 - Capable of monitoring their actions, diagnosing problems, and optimizing, reconfiguring, and repairing autonomously
 - Learn and adapt to improve their behavior over time
 - Includes acquiring, modifying, and transforming skills
 - May learn from humans, other IPS, or interactions with the environment
- Example:
 - A network of sensors with reconfigurable sensory platforms that can improve its
 capabilities over time based on the deployed environment

Ethical

- IPS that adhere to an ethical system of societal and legal norms
 - Capable of incorporating societal values into their reasoning
 - Recognize moral imperatives, and avoid commands and actions that violate those dictates
 - Correctly apply ethical decision making when multiple goals are in conflict
- Example:
 - An aerial vehicle is tracking a fugitive in a neighborhood; the vehicle must trade off the privacy concerns of citizens with its mission



Knowledge-Rich

- IPS that reason over a diverse body of knowledge
 - Capable of quantitative and qualitative reasoning, using highlevel semantics
 - Reason using multiple models
 - Includes symbolic, ontological, probabilistic, mixed, and commonsense reasoning models
 - Capable of introspectively reasoning about their own reasoning capabilities and limitations
- Example:
 - A smart grid that reasons about sensory load (numeric quantities), types of sensors (semantic knowledge), and anticipated events (commonsense reasoning)

Project Classes

Foundational:

- Research fundamental techniques, theories, and technologies that contribute to the development of IPS
- Must focus on at least one of the five research themes
- Not required to use a physical testbed, but must include evaluation plan

Integrative:

- Research into novel integration of two, or more, of the five research themes
- Required to evaluate on a physical testbed
- Multiple Pls, from different disciplines, are encouraged



Award Information

- Anticipated Funding of \$16.5M in FY 2017
- Foundational Projects
 - \$350K-\$700K total costs; up to three years
 - Expected to award 15–25 projects
- Integrative Projects
 - \$500K-\$1.4M total costs; up to four years
 - Expected to award 10–15 projects

Note that budget ranges <u>overlap</u> – do <u>not</u> choose project class based on budget requirements

What Proposals are Good Fits for S&AS

- The focus of this solicitation is on how planning, reasoning, self-awareness, and learning can lead to autonomous systems that require minimal human intervention and are adaptive to changes in environment, mission, and own capabilities
- Proposals must:
 - Address at least one of the five research themes
 - Include evaluation showing relevance to IPS
 - May include other themes

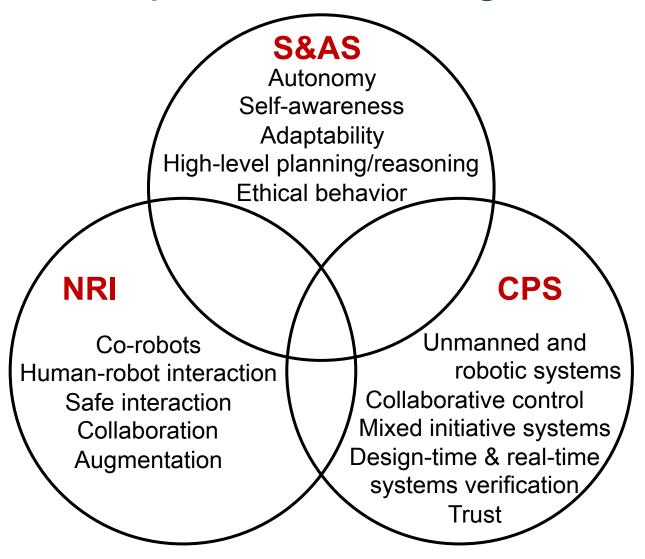


What Proposals are Not Good Fits for S&AS

- Proposals that focus primarily on
 - Purely software (non-embodied) agents
 - Hardware design and development
 - Low-level control
 - Formal verification and validation
 - Security



Relationships to Other Programs





Eligibility Requirements

- Universities and Colleges
 - Including community colleges
 - Accredited, and having a campus located, in the US
- Non-profit, non-academic organization
 - Independent museums, observatories, research labs, professional societies and similar organizations in the U.S. associated with educational or research activities
- At most two (2) S&AS proposals for any PI, co-PI, or Senior Personnel in a given year



Proposal Submission

- Proposal deadline: December 19, 2016 (due 5pm local time)
 - Refer to the solicitation
 - http://www.nsf.gov/pubs/2016/nsf16608/nsf16608.htm
 - Refer to "Proposal and Award Policies Procedures Guide"
 - https://www.nsf.gov/pubs/policydocs/pappguide/nsf16001
- Yearly PI meeting in Washington, DC
 - Account for travel in budget



Supplementary & Single Copy Documents

- Data Management Plan
- List of Project Personnel and Partner Institutions
 - List PIs, co-PIs, senior personnel, consultants, collaborators, subawardees, postdocs, advisory committee members
 - Lead PI submits
- Collaboration Plan
 - Any project with more than one (1) PI
 - Length commensurate with complexity of project
- Postdoctoral Mentoring Plan (if applicable)
- Collaborators and Other Affiliations (COA)
 - Single copy document for each PI, co-PI, senior personnel
 - Use Excel template at https://www.nsf.gov/cise/collab



Review Criteria

- For All Projects: Intellectual Merit
- For All Projects: Broader Impact
- For All Projects: Program Relevance
 - Explicitly address the goal of achieving Intelligent Physical Systems that exhibit a high degree of autonomy
- For Integrative Projects:
 - Innovation in the integration of the system
 - Evaluation plan, including testbed(s), proposed experiments, and evaluation metrics



Thanks!

To ask a question, please follow the operator's directions.

- Please send questions via email: <u>S&AS@nsf.gov</u>
- Presentation and FAQ will soon be made available on program website:

https://www.nsf.gov/funding/pgm_summ.jsp?pims_id=505325

